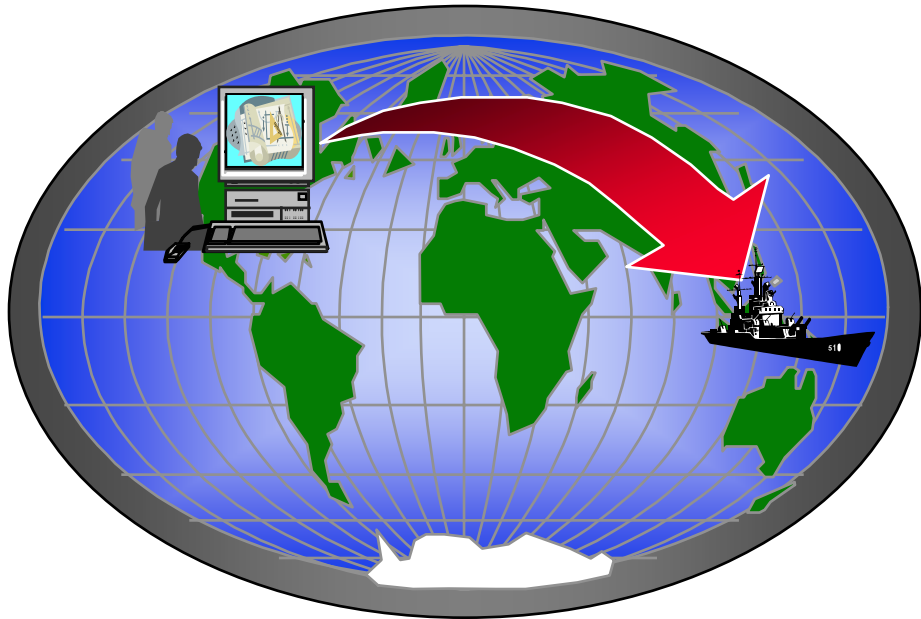




# Horizontal Integration based upon: Decentralized Data Fusion (DDF), NetCentric Architecture (NCA), and Analysis Collaboration Tools (ACT)



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# Horizontal Integration (HI)

## *Definition\**

**Processes and capabilities to acquire, synchronize, correlate, and deliver National Security Community data with responsiveness to ensure success across all policy and operational missions.**

**\* Approved by the HI Senior Steering Group, 18 October 2003**

# Technology Enablers for HI

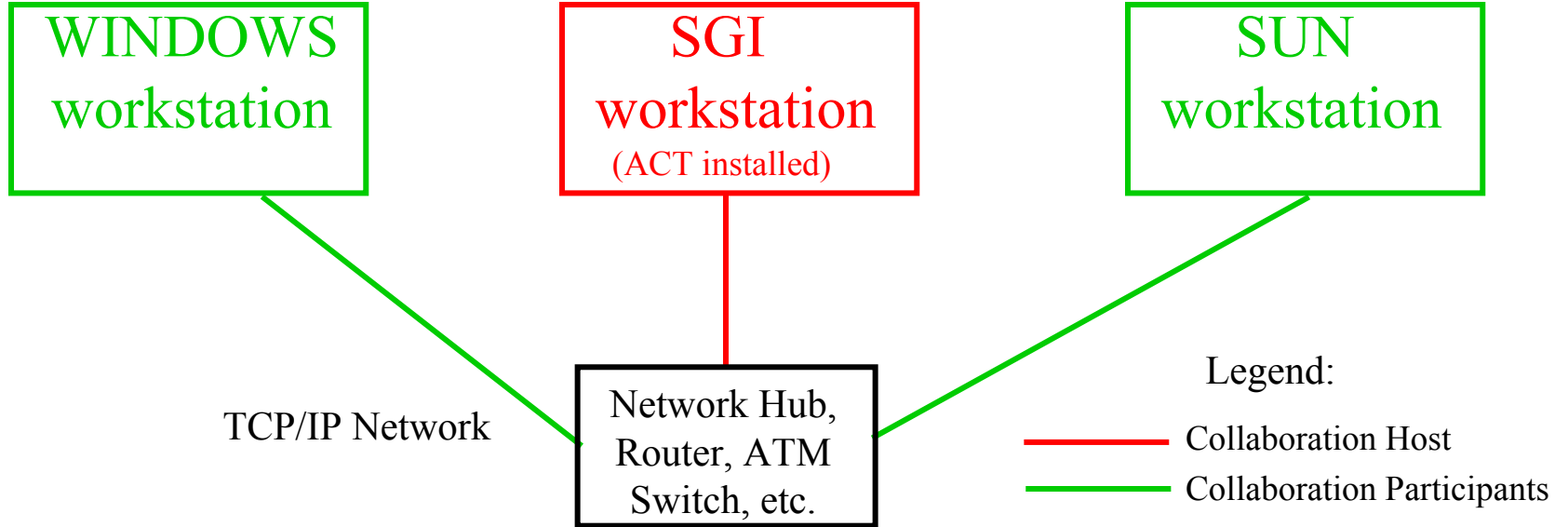
- **NetCentric Architecture (NCA)**
  - A Network Architecture that gives component platforms access to multi-level security information and communications over a two-way encrypted connection.
- **Decentralized Data Fusion (DDF)**
  - A framework which includes a solution to the data fusion problem.
  - Two components of the proposed framework are:  
Covariance Intersection (CI), and Covariance Union (CU)\*.
- **Analysis Collaboration Tool (ACT)**
  - NRL developed second-generation tool for application sharing and collaboration between intelligence analysts.

\*Julier, S. and Uhlmann, J., Handbook of Multisensor Data Fusion, 2001, edited by D.Hall and J. Llinas, Chap.12.

# Analysis Collaboration Tool (ACT)

- **Objective:**
  - Leverage COTS Collaboration Technologies to enable Real-Time Collaboration Capabilities for legacy and next generation Analysis Tools.
- **Approach:**
  - Utilize SGImeeting and SunForum COTS Collaboration Tools
  - Modify, if necessary, Legacy and Next Generation Analysis Tools to accommodate Functionality of COTS Collaboration Tools

# ACT Network Diagram



# ACT Results

- **ACT Enables Distributed Real-Time Collaboration for Legacy and Next Generation Analysis Tools.**
- **ACT enhances SGImeeting/Sunforum/NetMeeting Collaboration Capabilities:**
  - No additional software required by participants.
  - Any X Windows based Application can be Collaborated
  - No Application Source Code Changes Required.
  - Multi-platform Collaboration: SGI, SUN, Windows (95,98,NT, 2000),

# **The Problem of Distributed Information**

- **Current ‘stovepipe’ systems are structured to support relatively autonomous nodes.**
- **Each node incorporates data it needs to perform its function and then processes and transmits its best available information for use by other nodes.**
- **In many cases information is redundant.**
- **In some cases information is spurious and must be purged.**

# Decentralized Data Fusion (DDF)

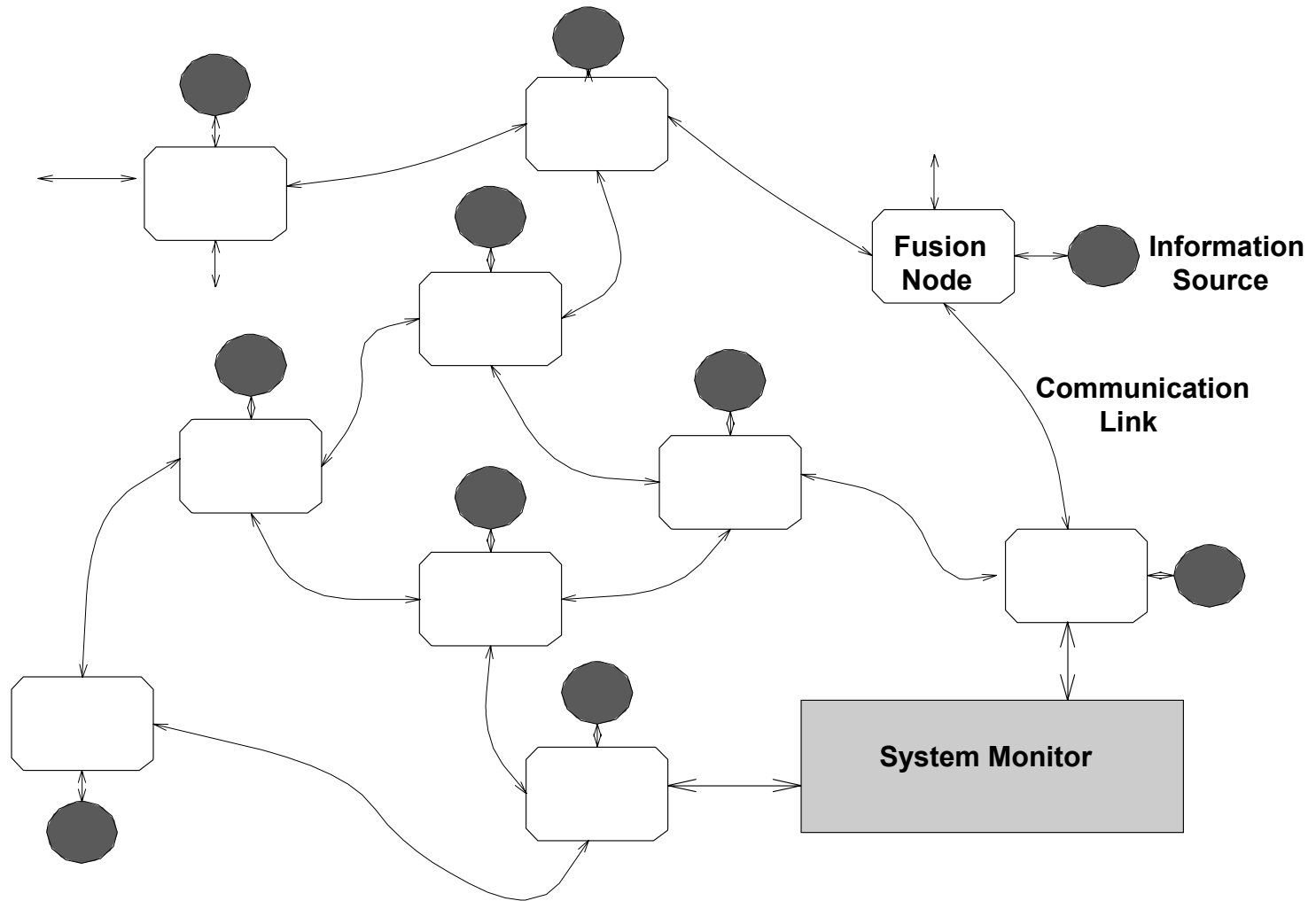
- A network-centric information management system includes links between a 'global' database and multiple local databases.
- A mechanism is needed to fuse correlated/redundant information so that database updates are *consistent*.
  - Covariance Intersection(CI) is proposed.
- A mechanism is needed to prevent the network from being undermined by inconsistent data (deconfliction problem).
  - Covariance Union (CU) is proposed.



# Key Requirements for DDF

- 1. The information (reports) must have a well-defined measure of uncertainty and confidence.**
- 2. The fusion process must ensure that the database updates maintained by all entities are consistent.**
- 3. The data fusion method must be robust to failures in the network caused by, for example, communications disruptions.**
- 4. The connectivity of the nodes can be dynamically changed.**
- 5. The data fusion framework must be efficiently scalable, e.g., to networks having many nodes.**

# A Distributed Data Fusion Network



- Each box represents a fusion node

# Covariance Intersection: What It Is

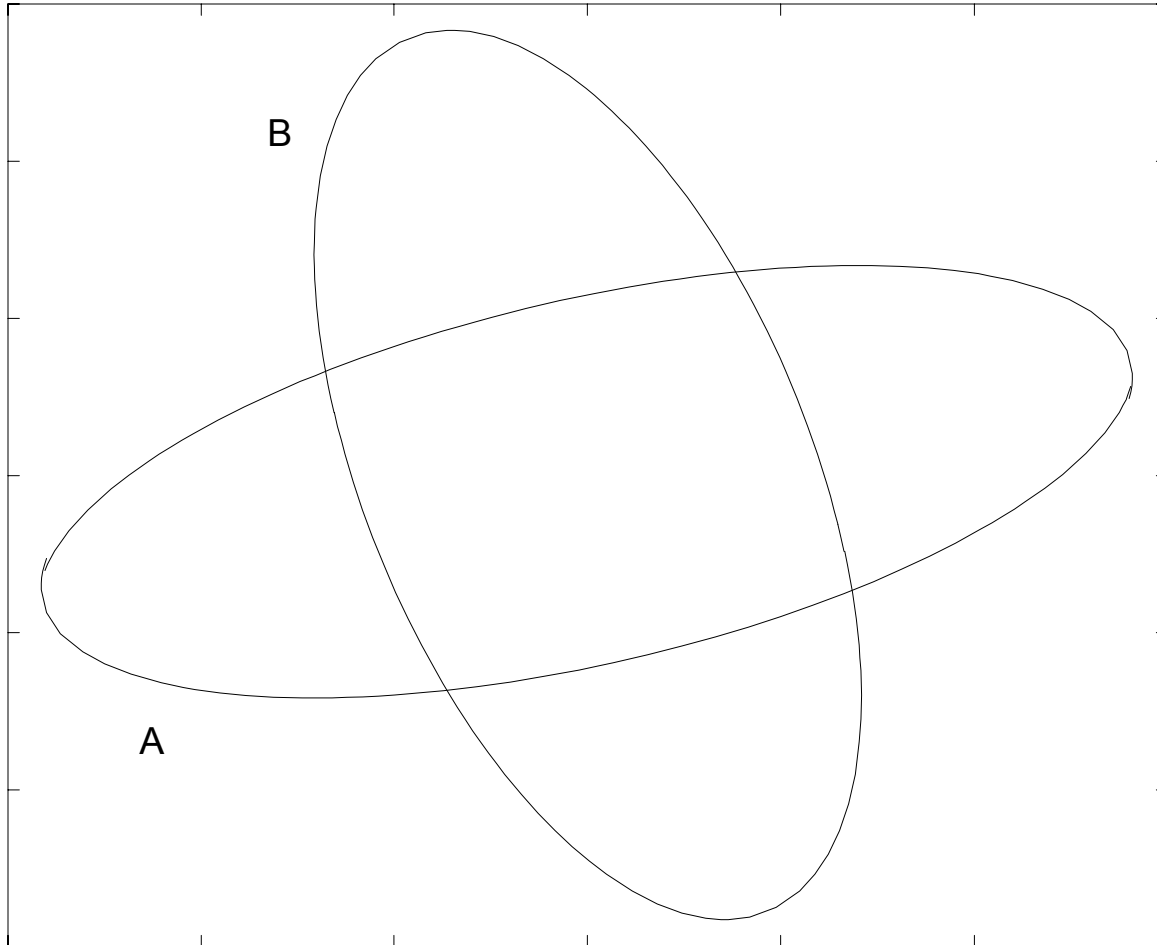
- Given mean and covariance pairs  $(a, A)$  and  $(b, B)$ , a fused estimate  $(c, C)$  is defined by CI as:

$$C = (w A^{-1} + (1-w)B^{-1})^{-1}$$

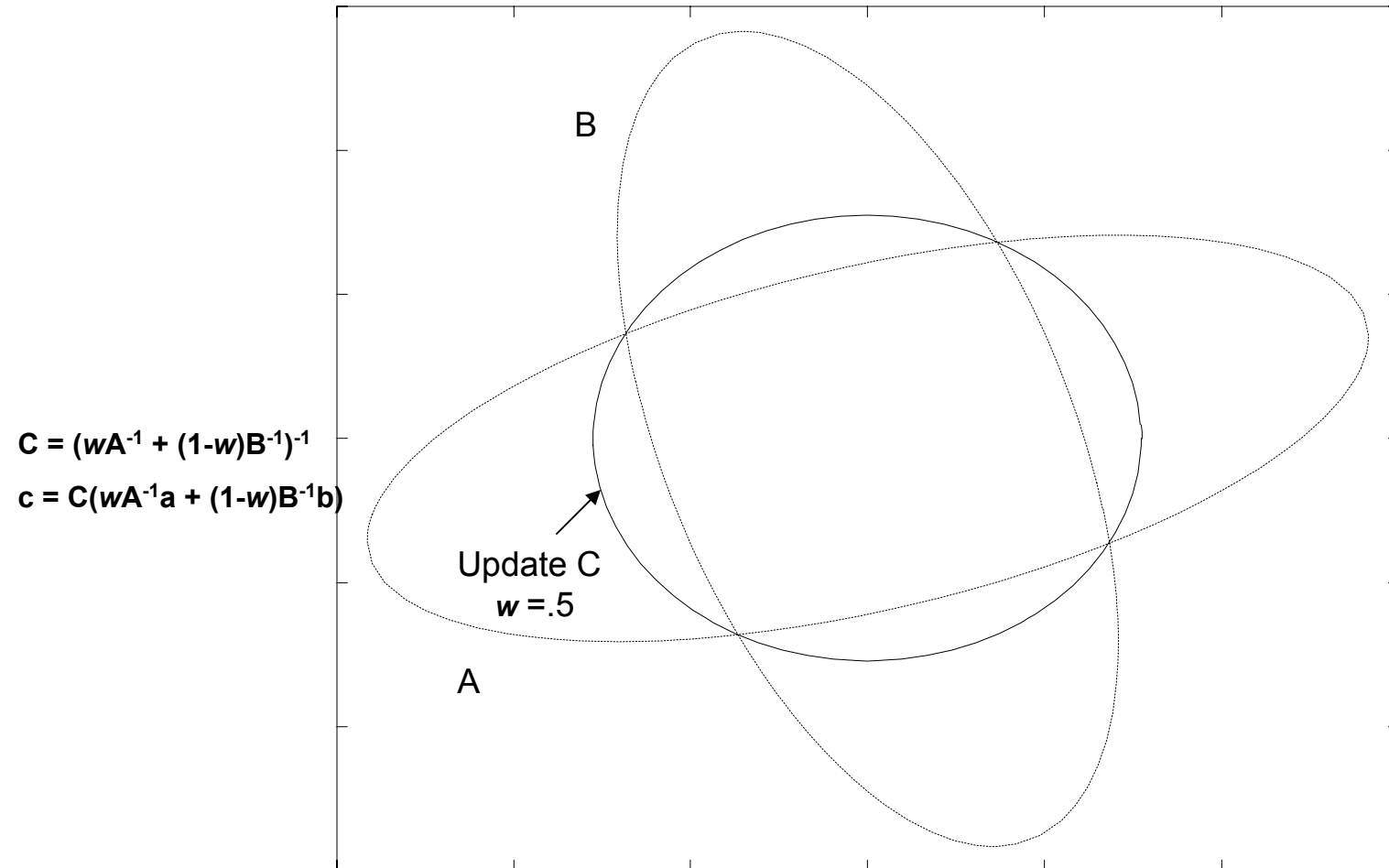
$$c = C(w A^{-1}a + (1-w)B^{-1}b)$$

The parameter  $0 \leq w \leq 1$  is determined by the covariance measure that is to be minimized (e.g., determinant or trace of  $C$ ).

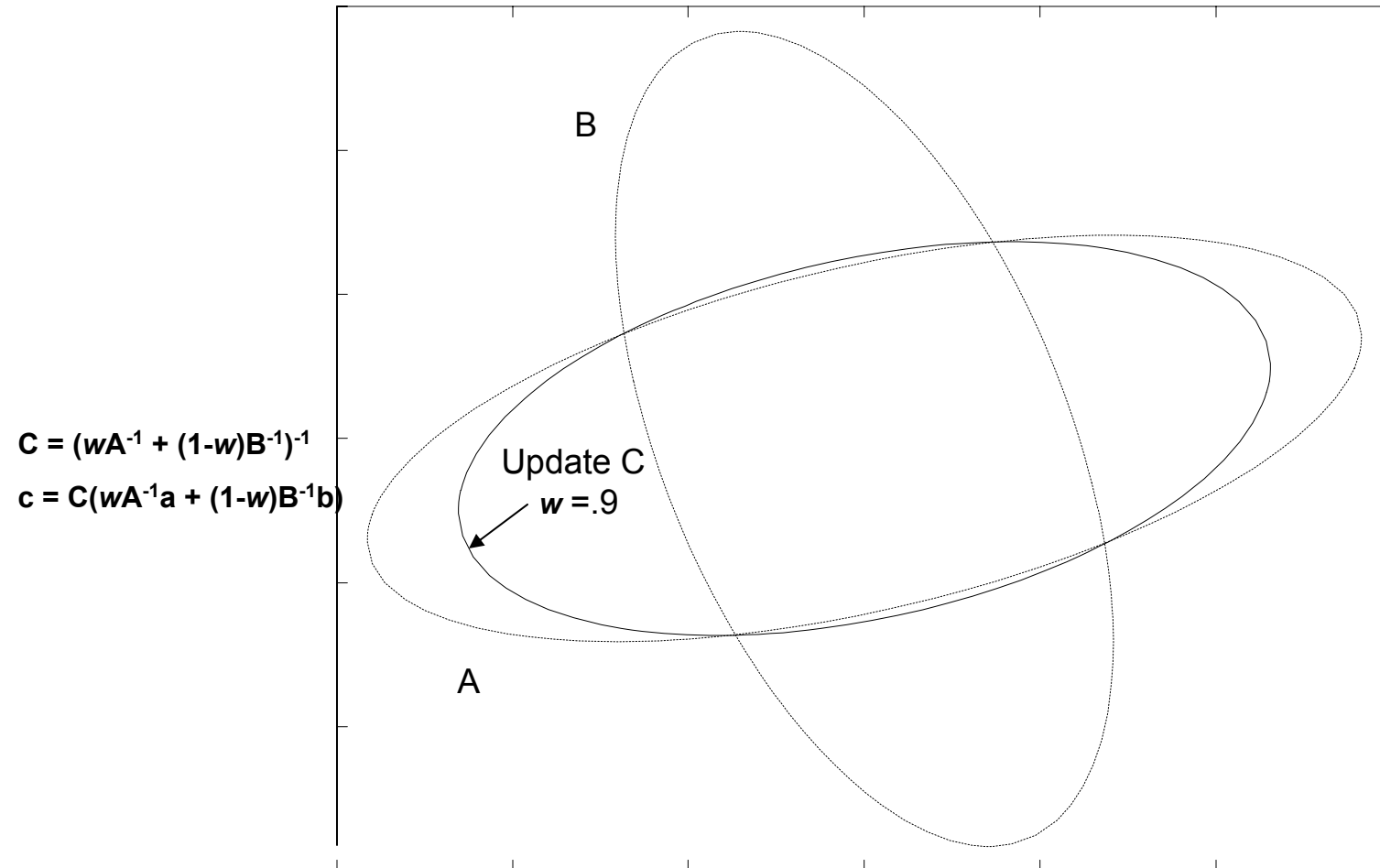
# Example: Error Ellipses (cont'd.)



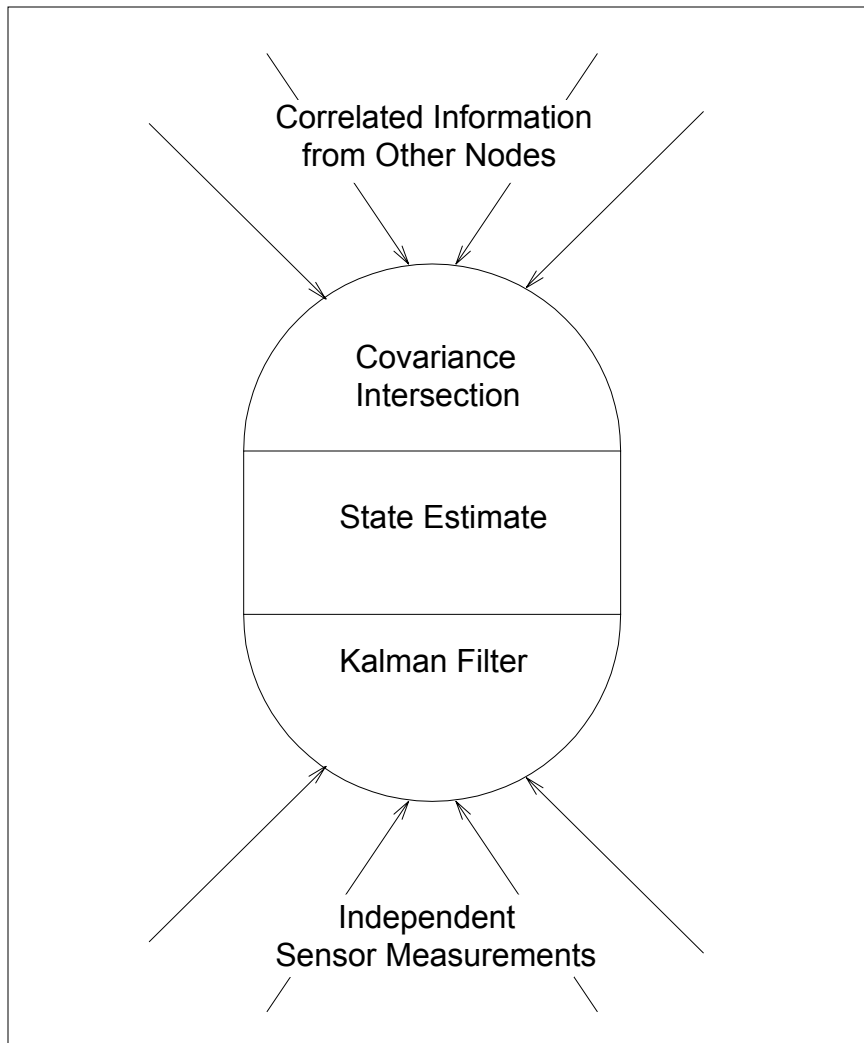
# Example: Error Ellipses (cont'd.)



# Example: Error Ellipses (cont'd.)



# A Canonical Node in a General Data Fusion Network



# Covariance Union (CU)

- Assume that in the database deconfliction problem only one mean and covariance estimate, either  $(\mathbf{a}, \mathbf{A})$  or  $(\mathbf{b}, \mathbf{B})$ , is a consistent estimate of the state of an object of interest. The other estimate,  $(\mathbf{a}, \mathbf{A})$  or  $(\mathbf{b}, \mathbf{B})$ , must be discarded.
- Because it is not generally possible to know which estimate is spurious, the only way to rigorously combine the estimates is to form a unioned estimate,  $(\mathbf{u}, \mathbf{U})$ , that is guaranteed to be consistent with respect to *both* of the two estimates.
- In other words, the estimate  $(\mathbf{u}, \mathbf{U})$  must be consistent if the estimate  $(\mathbf{a}, \mathbf{A})$  is correct and  $(\mathbf{b}, \mathbf{B})$  is spurious, and it must be consistent if  $(\mathbf{b}, \mathbf{B})$  is correct and  $(\mathbf{a}, \mathbf{A})$  is spurious. This estimate will be referred to as the Covariance Union (CU) of the two estimates.



# Covariance Union (CU) Equations

- Given two mean and covariance estimates,  $(\mathbf{a}, \mathbf{A})$  and  $(\mathbf{b}, \mathbf{B})$ , only one of which is known to be consistent, the Covariance Union (CU) estimate  $(\mathbf{u}, \mathbf{U})$  is defined as the mean vector  $\mathbf{u}$  with the smallest possible covariance matrix  $\mathbf{U}$  satisfying the inequalities:

$$\mathbf{U} \geq \mathbf{A} + (\mathbf{u}-\mathbf{a})(\mathbf{u}-\mathbf{a})^T$$

$$\mathbf{U} \geq \mathbf{B} + (\mathbf{u}-\mathbf{b})(\mathbf{u}-\mathbf{b})^T$$

- These inequalities are based on the observation that if the estimate  $(\mathbf{a}, \mathbf{A})$  is consistent, then the translation of the vector  $\mathbf{a}$  to  $\mathbf{u}$  will require its covariance to be enlarged by the addition of a matrix at least as large as the outer product of  $(\mathbf{u}-\mathbf{a})$  in order to be consistent. The same reasoning applies if the estimate  $(\mathbf{b}, \mathbf{B})$  is consistent.

# DDF Summary

- A Decentralized Data Fusion (DDF) framework, as a key enabler for HI, has been proposed.
- The DDF paradigm is based upon the concepts of covariance intersection (CI) and covariance union (CU).
- CI always produces a consistent fused estimate with no assumptions regarding correlation required.
- CU provides the first provably rigorous and optimal solution to the database deconfliction problem.
- In the context of the DDF framework for HI, work still remains to develop efficient and robust implementations and applications of CI and CU.