



A Situation Analysis Toolbox for Course of Action Evaluation

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Outline

1. Formalisation of the Situation Analysis process
 - Situation, Situation awareness, Situation analysis
2. Situation Analysis Toolbox (SAT) implementing the previous theoretical concepts
 - Modeling situation as a pursuit-evasion game
 - Counter-smuggling vignette
 - Five Modules
 - 1) *Behaviour simulation toolbox*
 - 2) *Discretisation toolbox*
 - 3) *State generation toolbox*
 - 4) *State searching toolbox*
 - 5) *Visualization toolbox*
3. Conclusions



Interpreted Systems Semantics for situation analysis

Interpreted systems semantics is an epistemic logical approach proposed in the 1995 for the analysis of distributed systems by **Fagin, Halpern, Moses and Vardi**

R. Fagin, J. Y. Halpern, Y. Moses, and M. Y. Vardi. Reasoning about knowledge. The MIT Press, Cambridge, MA, 2003.

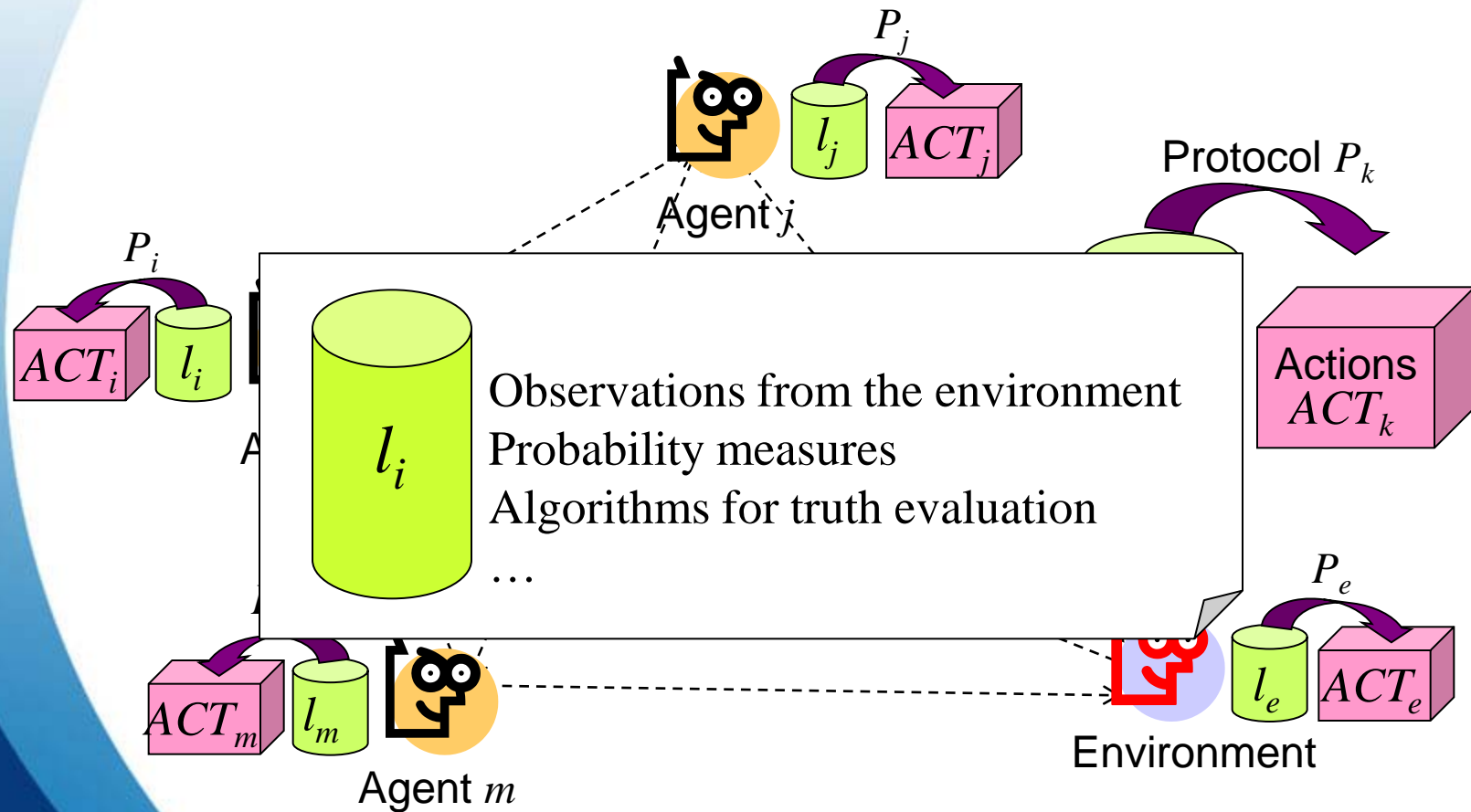


Interpreted Systems Semantics for situation analysis

- Hypothesis: *Interpreted Systems Semantics is a general framework for situation analysis and high-level information fusion applications*
- Arguments:
 - Designed for **distributed systems** analysis;
 - **Situations** are adequately represented by state transition systems;
 - The notions of Situation, Situation Awareness and Situation Analysis can be **formally defined**;
 - Allows reasoning about **knowledge, uncertainty and time**;
 - The framework is general enough so that **Generalized Information Theory** can be **framed** into ISS;
 - Can take advantage of both **model checking** and inductive decision **procedures**.

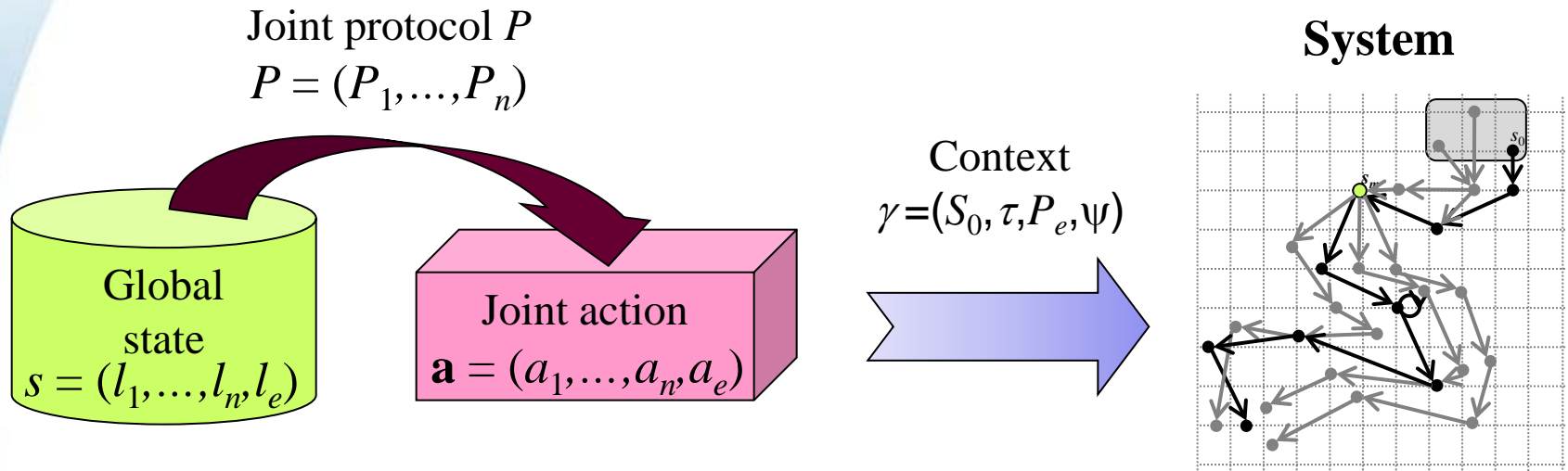


Elements of the model (1)





Elements of the model (2)



$$\mathcal{I} = \langle S, P, \gamma, \pi \rangle$$

π is an interpretation function for formulas in $\mathcal{L}(\Phi)$

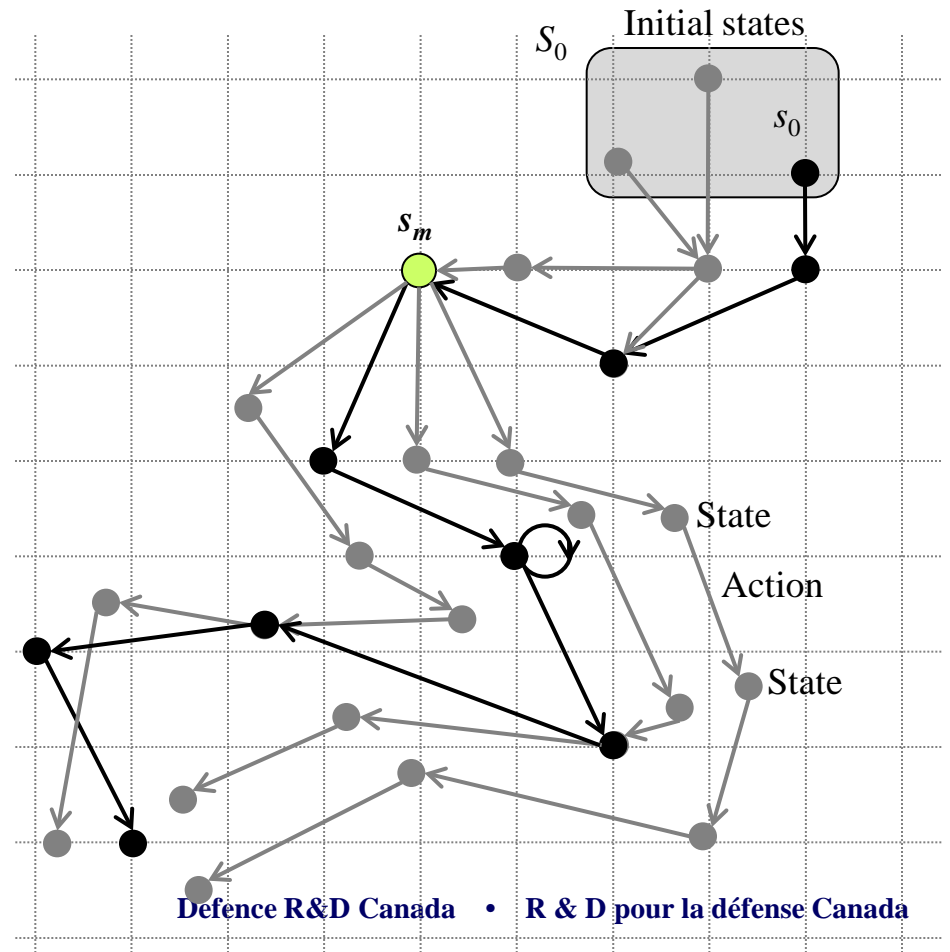


Situation

A *situation* is the subsystem $\mathcal{I}(r,m)$ of \mathcal{I} , that is the system representing P in the interpreted context $(\gamma_{(r,m)}, \pi)$

3 remarkable cases:

1. Global state
2. Given a single initial state
3. Full spectrum of possible paths





Awareness as resource-boundedness

An agent is *aware* of a formula ϕ if it is able to compute its truth value

$$(\mathcal{I}, r, m) \models A_i \phi \text{ iff } A_i(\phi, l_i) \neq \text{"?"}$$

Algorithm for truth evaluation

$$A_i = \text{alg}_i(r, m)$$

$$\text{with } A_i(\phi, l_i) = \begin{cases} \text{Yes if } \phi \text{ is true} \\ \text{No if } \phi \text{ is false} \\ \text{? if the agent is unable to compute} \end{cases}$$

Local data = Observations

$$l_i = \text{obs}_i(r, m)$$

→ The fact that the algorithm can compute the truth value of ϕ does not mean that this is the correct truth value.

→ Awareness is a practical notion of knowledge



Situation analysis (*proposed approach*)

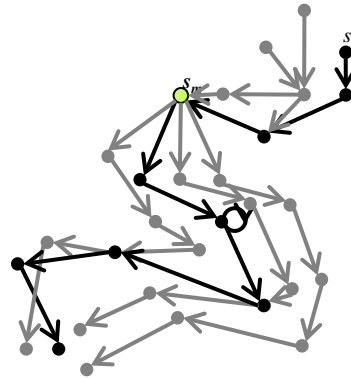
Situation analysis is the process of verifying properties of the interpreted system expressed by a formula ϕ_{KT}

$$(\mathcal{I}, r, m) \models \phi_{KT}$$



Queries

- Is ϕ true ?
- Will ϕ be true at all future steps ?
- Is ϕ always true ?
- Does Agent 1 knows ϕ ?
- Does everybody in group G knows ϕ ?



Situation

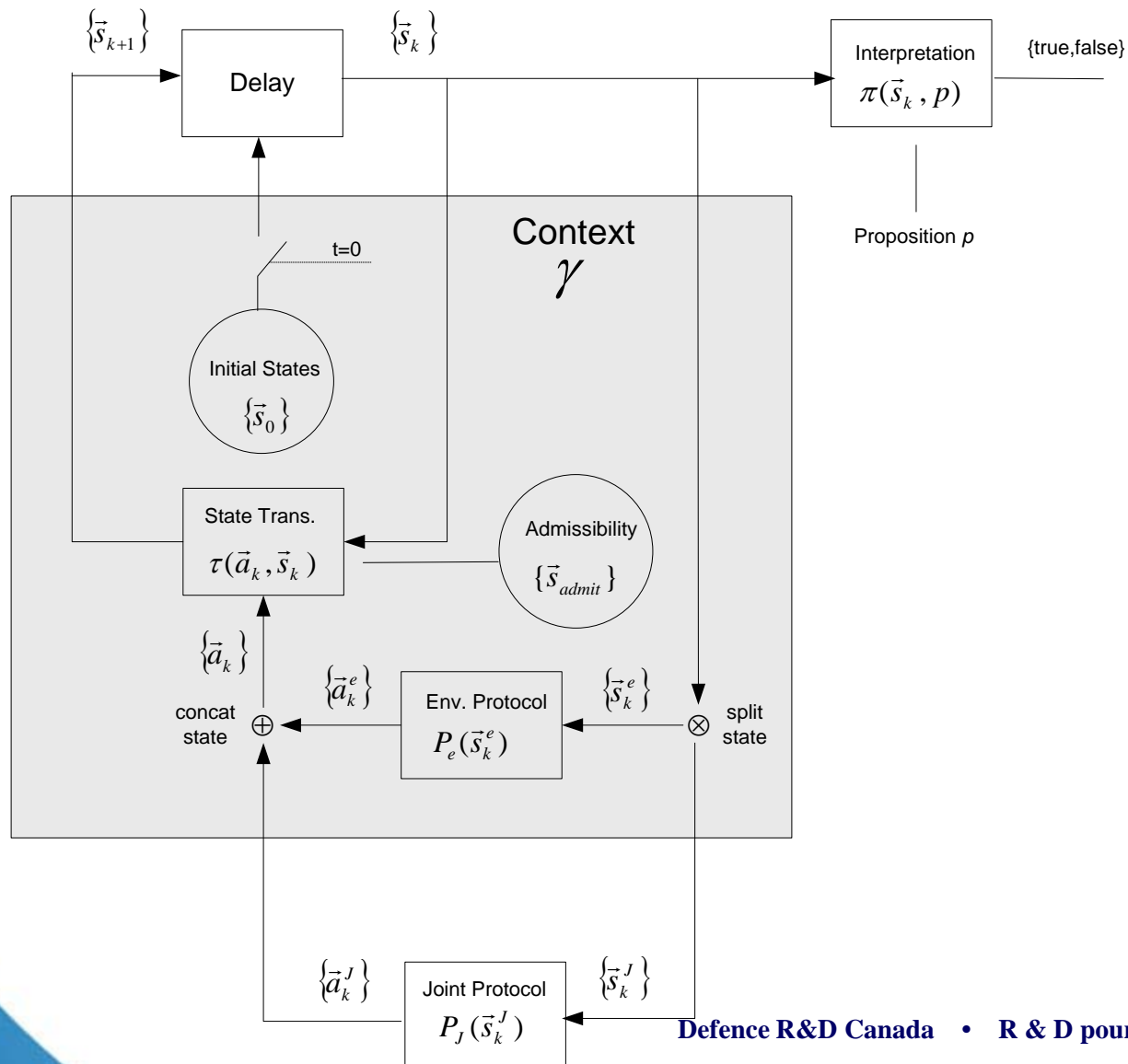


YES

NO



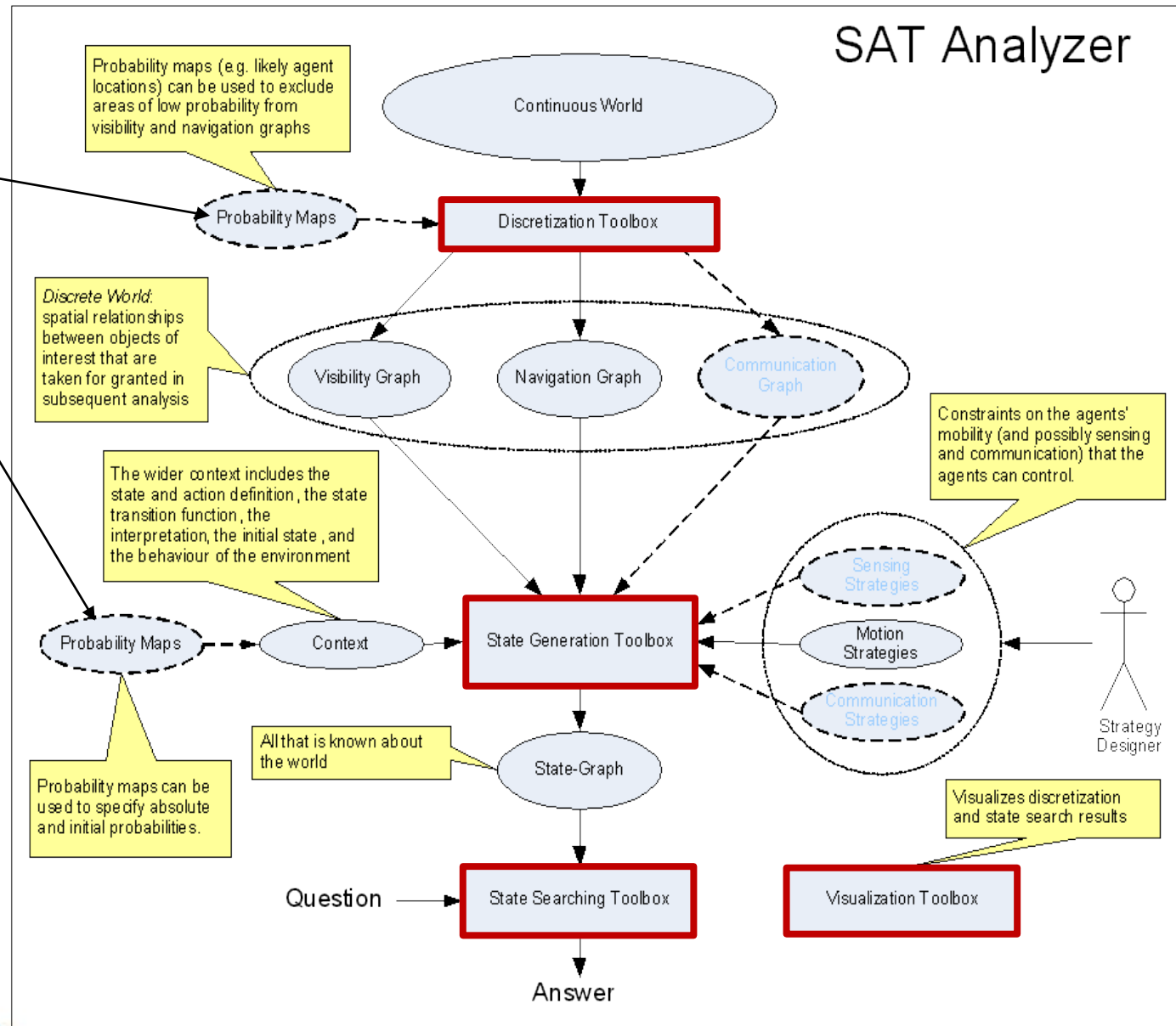
Engineer view of Interpreted Systems





SAT – A Situation Analysis Toolbox

5 modules





SAT – A Situation Analysis Toolbox

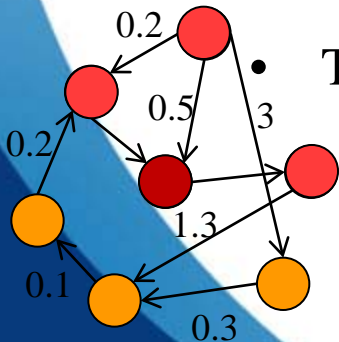
2 purposes:

1. Situation **generation**
2. Situation **analysis**



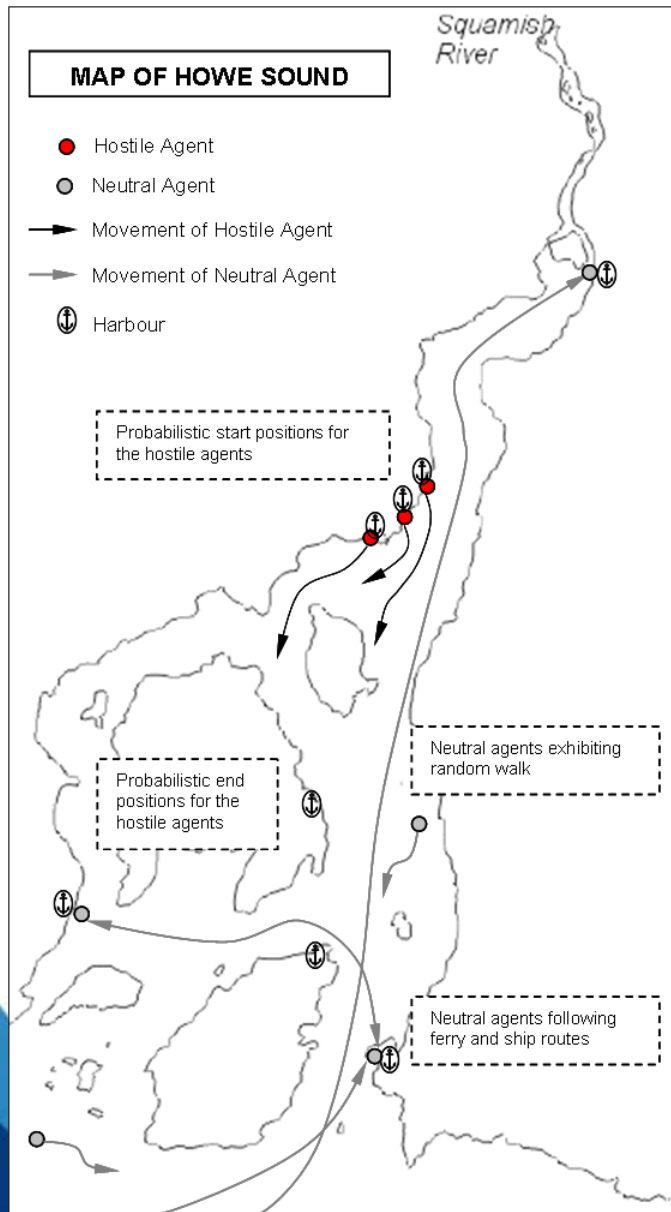
Situations as pursuit-evasion (PE) games

- Pursuer and evader agents are constrained to move within a **graph** whose nodes are possible locations and whose edges denote paths between two locations.
- PE consists in a game between two teams having opposite goals, the players jointly seeking to maximize (resp. to minimize) a function of distance.
- Each agent has a **visibility** sensor of sensing range r meaning that the agent can see a node if it is within its range.
- Capture occurs when a pursuer and the evader are at the same position (node) at the same time.
- Basic action: Move from one node to an adjacent node.
- The evader's strategy P_e is unknown to the pursuers.





Counter-smuggling vignette



A smuggling operation has been reported in Howe Sound (north-west of Vancouver on Canada's West Coast).

Can we guarantee that the smugglers will be detected ?



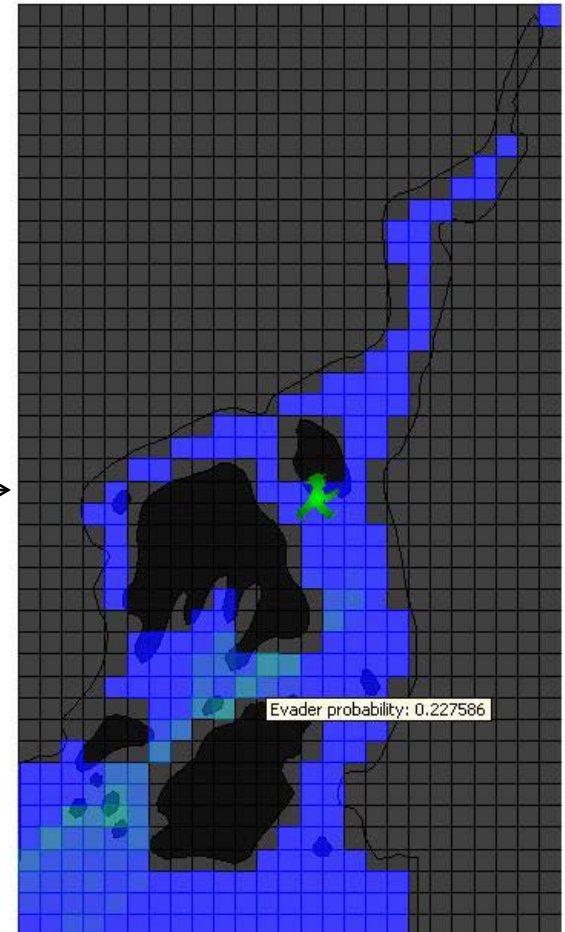
SAT – Behaviour Simulation Toolbox



Continuous world
(GIS map)

Partial knowledge
on evader's behaviour

Behaviour
simulator

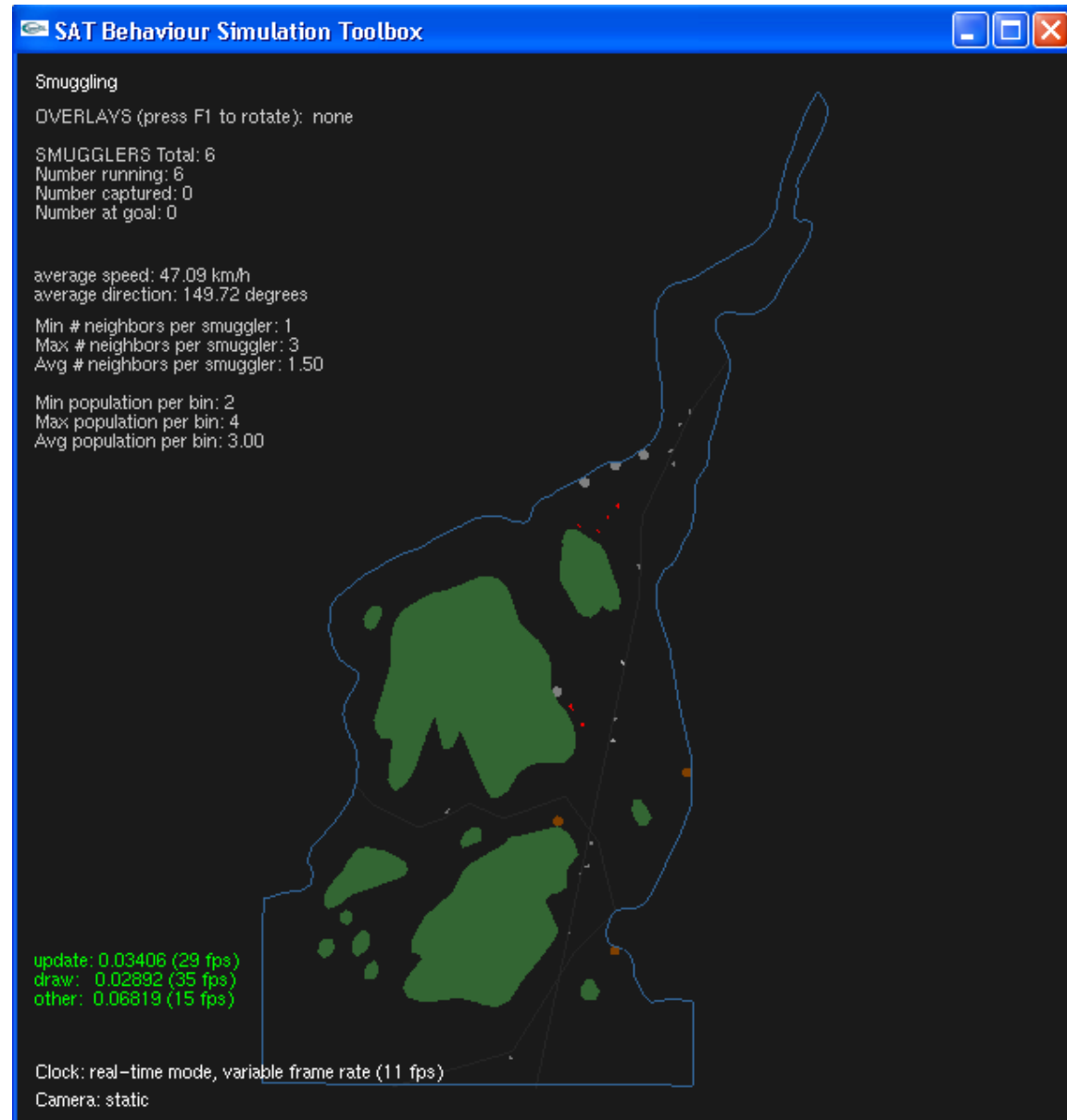


Probability map
(agent containment)



SAT – *Behaviour Simulation Toolbox*

Opensteer library

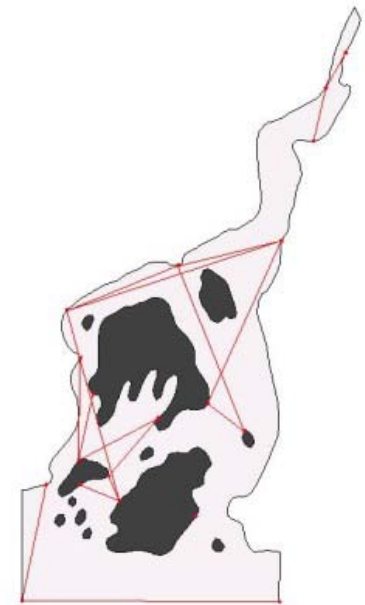




SAT – *Discretisation Toolbox*



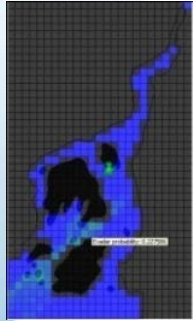
Discretiser



Visibility graph
Navigation graph



SAT - *The State Generation Toolbox*



```

case of
  if PosP=PosE do  $\Lambda$ 
  if PosE  $\in$  Voisinage(PosP) do Move-to(PosE)
  else Move-to(n'importe quel neud adjacent)
  Observe
end case

```

Context



```

case of
  if PosP=PosE do  $\Lambda$ 
  if PosE  $\in$  Voisinage(PosP) do Move-to(PosE)
  else Move-to(n'importe quel neud adjacent)
  Observe
end case

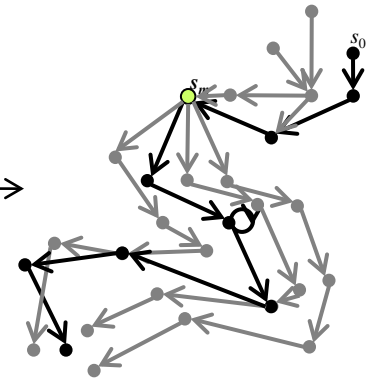
```

Joint strategy

γ

P

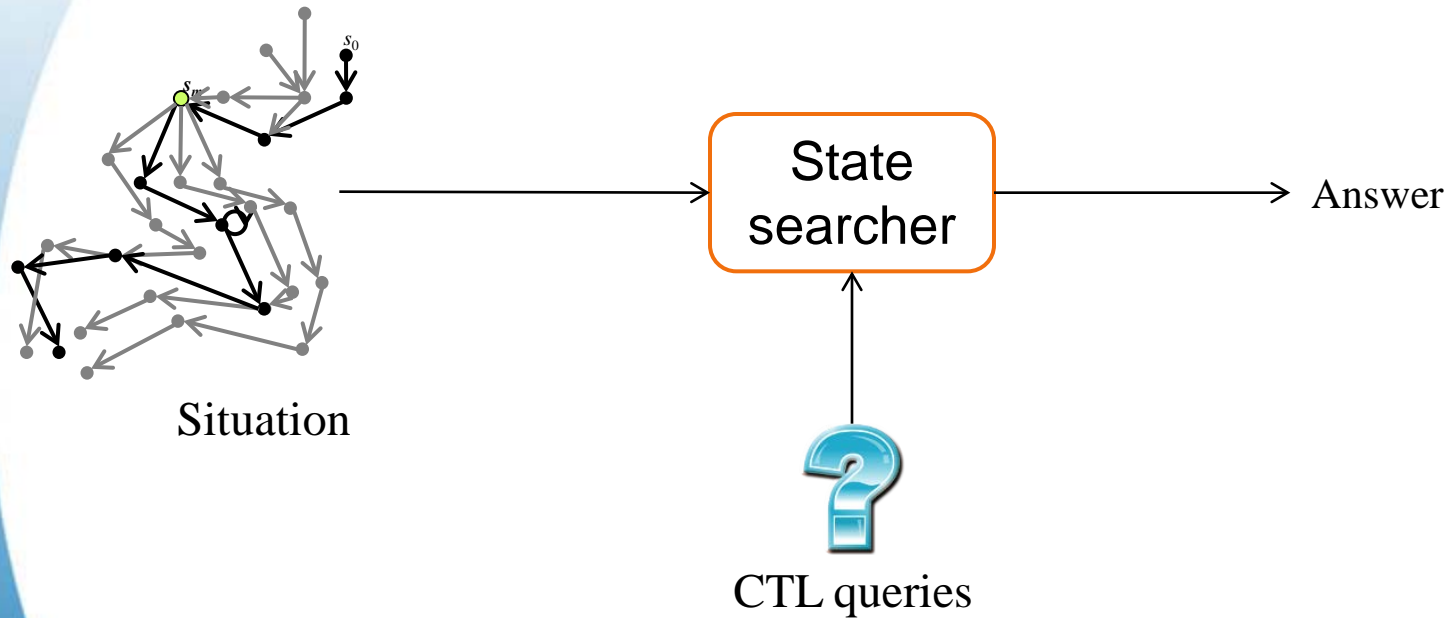
State generator



Situation
(state transition system)



SAT – State Searching Toolbox



AX ϕ	ϕ in all next states.
EX ϕ	ϕ in at least one next state.
A [ϕ U ψ]	on all paths, ϕ until ψ .
E [ϕ U ψ]	on at least one path, ϕ until ψ .
AF ϕ	On all paths, in some future state, ϕ .
EF ϕ	On at least one path, in some future state, ϕ .
AG ϕ	On all paths, in all future states, ϕ .
EG ϕ	On at least one path, in all future states, ϕ .



SAT – *Vizualisation Toolbox*

The screenshot shows the SAT P/E Visualizer interface. The main window displays a map with a path of green and purple squares. A text box in the center explains the CTL operators: ϕ : PursuitStateAllClear, **EX** ϕ : ϕ in at least one next state, and **EF** ϕ : On at least one path, ϕ in some future state. A dialog box titled "CTL query" is open, showing the query "AG ~ pursuitStateAllClear". The status bar at the bottom indicates "3 / 3 / 3".

Start: (468665.660974027,5471287.136601858)
Query "EX pursuitStateAllClear" returned false.
Query "EF pursuitStateAllClear" returned false.

ϕ : PursuitStateAllClear
EX ϕ : ϕ in at least one next state
EF ϕ : On at least one path, ϕ in some future state

CTL query
Enter a CTL query:
AG ~ pursuitStateAllClear
OK Cancel

Reset Step Back Step Play 3 / 3 / 3



Conclusions

- The Situation Analysis Toolbox (SAT) implements formal notions of situation analysis based on epistemic state transition systems.
- The SAT **generates** situations based on
 1. an abstract version of the environment (visibility graph) enriched with probability maps of presence of agents, built through modeling emerging behaviour.
 2. the execution of a joint strategy derived from pursuit-evasion game theory.
- The SAT **analyses** the situation through logical queries.

Further works:

- Epistemic and probabilistic queries
- Customise to account for other applications

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SAT - *Vizualizer*

